

Mechanism reduction methods based on time scale separation

3rd part

Dimitris A. Goussis

National Technical University of Athens, Greece



NTUA

Outline

1. Mathematical background
2. Time scales
3. Traditional reduction tools and their limitations
4. New algorithmic tools
5. Various methodologies
6. Applications
7. Quasi steady-state and partial equilibrium approx.

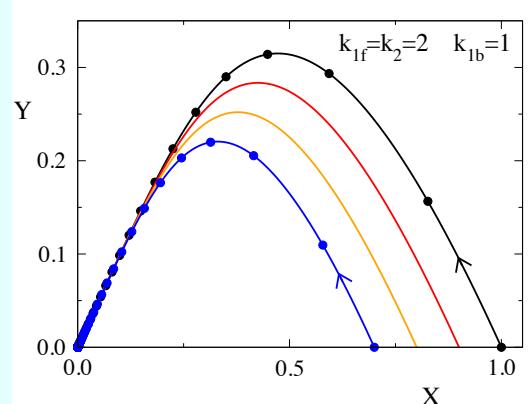


Some common features

$$\varepsilon = 10^{-6}$$

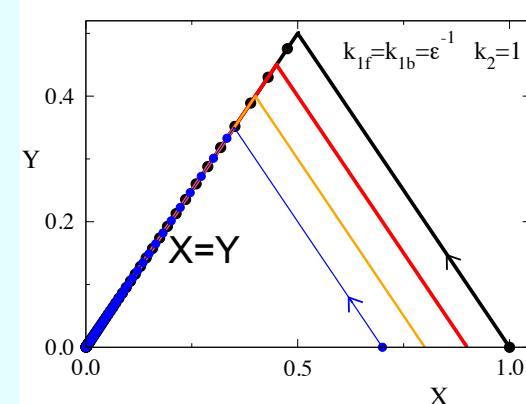
$$\tau_1 / \tau_2 = 0.25$$

$$\lambda_1 = -4$$



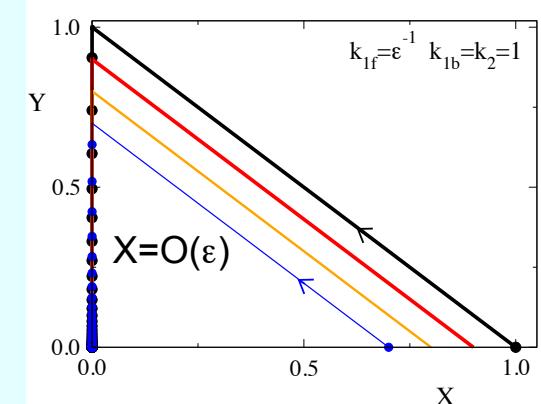
$$\tau_1 / \tau_2 = \varepsilon / 4$$

$$\lambda_1 = -2/\varepsilon$$



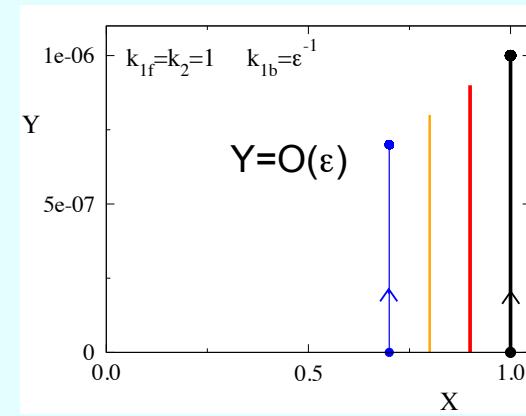
$$\tau_1 / \tau_2 = \varepsilon$$

$$\lambda_1 = -1/\varepsilon$$



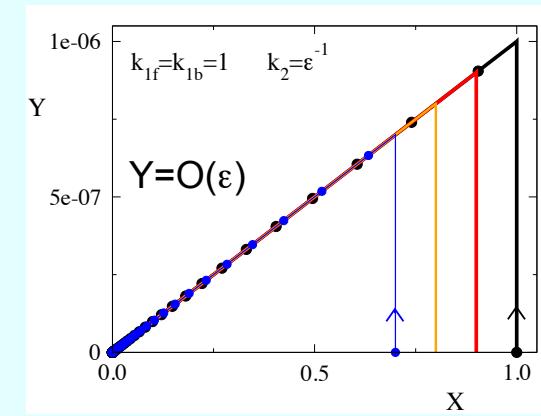
$$\tau_1 / \tau_2 = \varepsilon^2$$

$$\lambda_1 = -1/\varepsilon$$



$$\tau_1 / \tau_2 = \varepsilon$$

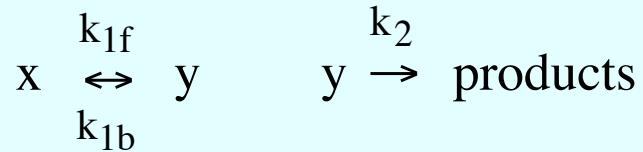
$$\lambda_1 = -1/\varepsilon$$



- 1. Time scale gaps
- 2. Dissipative time scales
- 3. Fast/slow behavior
- 4. Structures in phase space



Partial Equilibrium Approximation (1st reaction)



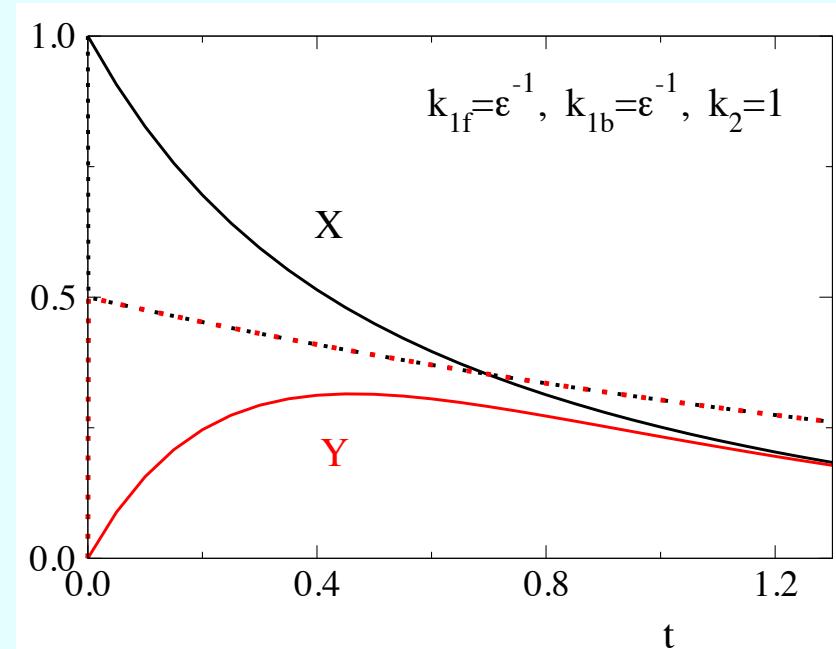
$$\frac{d}{dt} \begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} -1 \\ +1 \end{bmatrix} \left(\frac{X - Y}{\varepsilon} \right) + \begin{bmatrix} 0 \\ -1 \end{bmatrix} Y \quad \varepsilon = 10^{-6}$$

$$X - Y = O(\varepsilon)$$

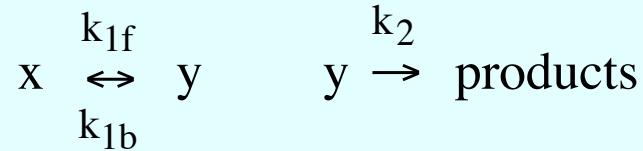
$$X - Y = O(\varepsilon) \Rightarrow \frac{dX}{dt} - \frac{dY}{dt} = O(\varepsilon)$$

$$\frac{X - Y}{\varepsilon} = \frac{Y}{2} + O(\varepsilon)$$

$$\frac{dX}{dt} = -\frac{X}{2} + O(\varepsilon) \quad \frac{dY}{dt} = -\frac{Y}{2} + O(\varepsilon)$$



Quasi Steady-State approximation (X)



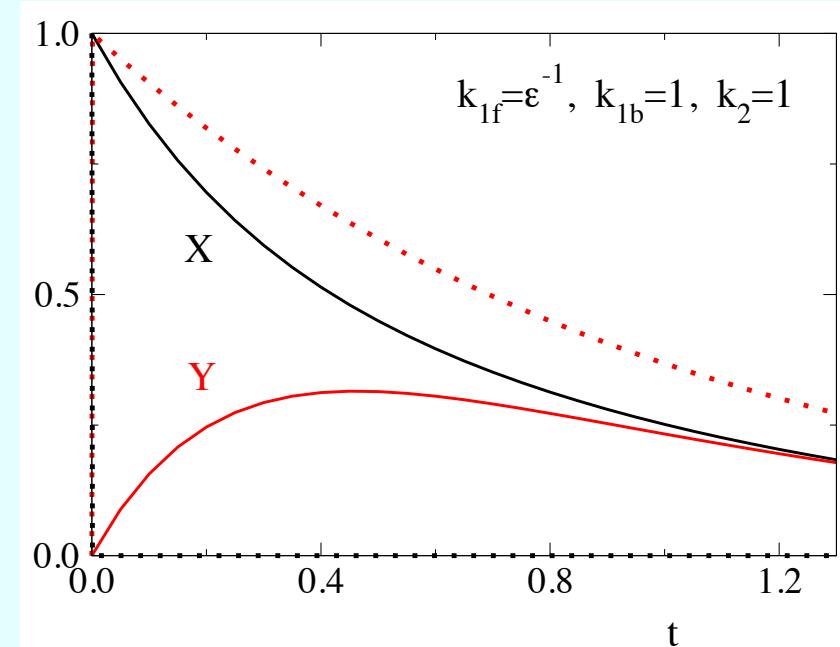
$$\frac{d}{dt} \begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} -1 \\ +1 \end{bmatrix} \left(\frac{X}{\varepsilon} - Y \right) + \begin{bmatrix} 0 \\ -1 \end{bmatrix} Y \quad \varepsilon = 10^{-6}$$

$$X = O(\varepsilon)$$

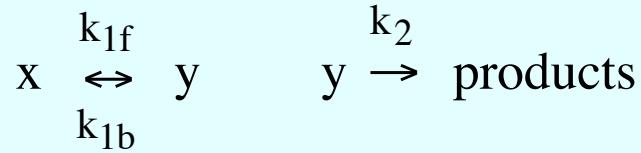
$$X = \varepsilon Z \Rightarrow \frac{dZ}{dt} = -\left(\frac{Z - Y}{\varepsilon} \right) \quad \frac{dY}{dt} = (Z - Y) - Y$$

$$Z - Y = O(\varepsilon)$$

$$\frac{X}{\varepsilon} - Y = O(\varepsilon) \quad \frac{dY}{dt} = -Y + O(\varepsilon)$$



Quasi Steady-State approximation (Y 1st)



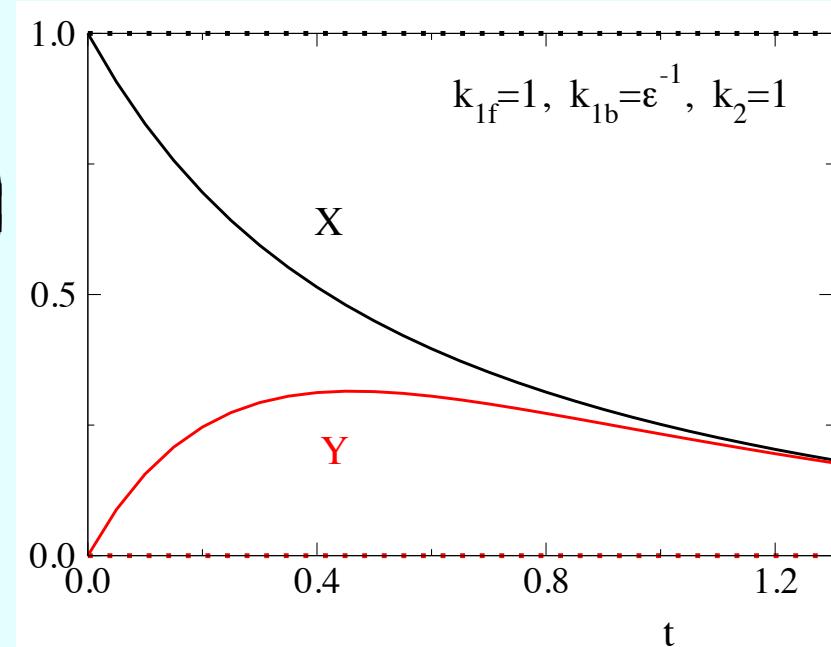
$$\frac{d}{dt} \begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} -1 \\ +1 \end{bmatrix} \left(X - \frac{Y}{\varepsilon} \right) + \begin{bmatrix} 0 \\ -1 \end{bmatrix} Y \quad \varepsilon = 10^{-6}$$

$$Y = O(\varepsilon)$$

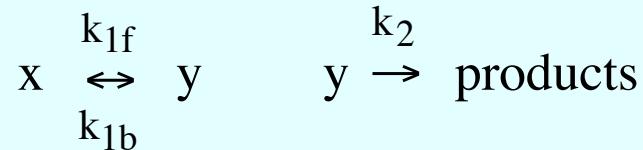
$$Y = \varepsilon Z \Rightarrow \frac{dX}{dt} = -(X - Z) \quad \frac{dZ}{dt} = \left(\frac{X - Z - \varepsilon Z}{\varepsilon} \right)$$

$$X - Z - \varepsilon Z = O(\varepsilon)$$

$$X - \frac{Y}{\varepsilon} = O(\varepsilon) \quad \frac{dX}{dt} = -Y + O(\varepsilon)$$



Quasi Steady-State approximation (Y 2nd)



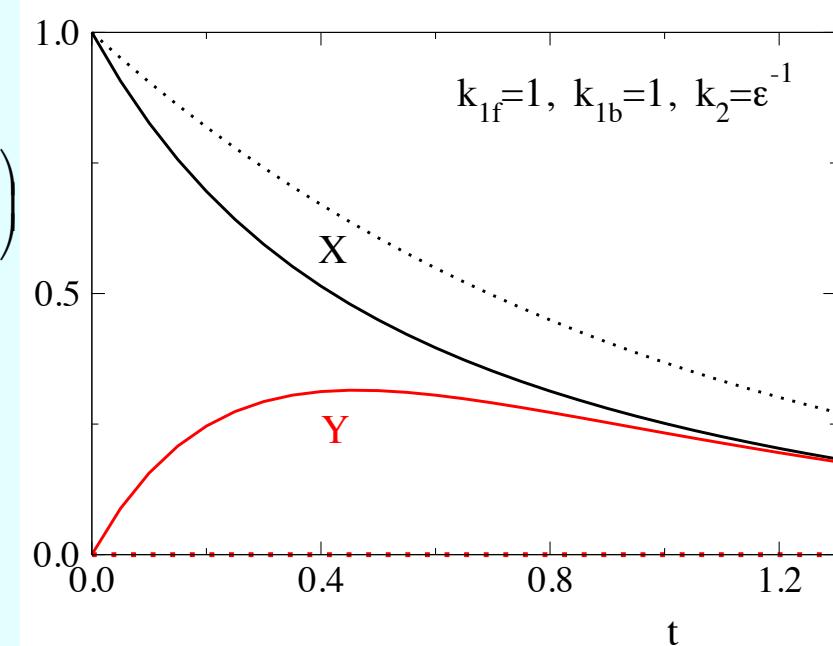
$$\frac{d}{dt} \begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} -1 \\ +1 \end{bmatrix} (X - Y) + \begin{bmatrix} 0 \\ -1 \end{bmatrix} \frac{Y}{\varepsilon} \quad \varepsilon = 10^{-6}$$

$$Y = O(\varepsilon)$$

$$Y = \varepsilon Z \Rightarrow \frac{dX}{dt} = -(X - \varepsilon Z) \quad \frac{dZ}{dt} = \left(\frac{X - \varepsilon Z - Z}{\varepsilon} \right)$$

$$X - Z - \varepsilon Z = O(\varepsilon)$$

$$X - \frac{Y}{\varepsilon} = O(\varepsilon) \quad \frac{dX}{dt} = -Y + O(\varepsilon)$$



QSSA/PEA literature

Bodenstein, Lind, Z. Phys. Chem. 57:168, 1906

Bodenstein, Z. Phys. Chem. 85:327, 1913

Michaelis and Menten, Biochem. Z. 49:333, 1913

Underhill and Chapman, J. Chem. Soc. Trans., 103:496, 1913

Briggs and Haldane, Biochem. J., 19:338, 1925

Acrivos, Benson, Bowen, Deakin, Frank-Kamenetskii, Fraser, Ignetik,
Goddard, Goldbeter, Klonowski, Maini, Oppenheim, Oran, Rein, Roussel,
Schnell, Segel, Slemrod, Tomlin, Turanyi, Tzafriri, Walcher

In combustion: Peters, Williams, Oran, Trevino, Turanyi/Tomlin



The nature of the QSSA/PEA

$$\frac{dy}{dt} = S_1 R^1 + S_2 R^2 + \dots + S_K R^K = [S_1 \dots S_M] \begin{bmatrix} R^1 \\ \vdots \\ R^M \end{bmatrix} + [S_{M+1} \dots S_K] \begin{bmatrix} R^{M+1} \\ \vdots \\ R^K \end{bmatrix}$$

$$= \underbrace{S_r R^r}_{\text{M fast reactions}} + S_s R^s$$

$$y = \begin{bmatrix} y^r \\ y^s \end{bmatrix} \quad \xleftarrow{\text{M fast species}}$$

$$\frac{d}{dt} \begin{bmatrix} y^r \\ y^s \end{bmatrix} = \begin{bmatrix} S_r^r \\ S_r^s \end{bmatrix} R^r + \begin{bmatrix} S_s^r \\ S_s^s \end{bmatrix} R^s$$

QSSA

PEA

Accuracy $O(\varepsilon)$

$$\varepsilon = \frac{\tau_M}{\tau_{M+1}}$$



The nature of the QSSA/PEA

$$\frac{dy}{dt} = S_1 R^1 + S_2 R^2 + \dots + S_K R^K = \boxed{S_r R^r} + S_s R^s$$

$$\frac{d}{dt} \begin{bmatrix} y^r \\ y^s \end{bmatrix} = \begin{bmatrix} S_r^r \\ S_r^s \end{bmatrix} R^r + \begin{bmatrix} S_s^r \\ S_s^s \end{bmatrix} R^s \rightarrow R^r = (S_r^r)^{-1} \left(\frac{dy^r}{dt} - S_s^r R^s \right)$$

= 0 $\neq 0$

QSSA PEA

QSSA:

$$R^r = -(S_r^r)^{-1} S_s^r R^s$$

$$\frac{dy^s}{dt} = (S_s^s - S_s^s (S_r^r)^{-1} S_s^r) R^s$$

$$S_r^r R^r + S_s^r R^s = 0$$

$$\frac{dy^r}{dt} \neq 0$$



The nature of the QSSA/PEA

$$\frac{dy}{dt} = S_1 R^1 + S_2 R^2 + \dots + S_K R^K = \boxed{S_r R^r} + S_s R^s$$

$$\frac{d}{dt} \begin{bmatrix} y^r \\ y^s \end{bmatrix} = \begin{bmatrix} S_r^r \\ S_r^s \end{bmatrix} R^r + \begin{bmatrix} S_s^r \\ S_s^s \end{bmatrix} R^s \rightarrow R^r = (S_r^r)^{-1} \left(\frac{dy^r}{dt} - S_s^r R^s \right)$$

= 0 $\neq 0$

QSSA PEA

PEA:

$$R^r = \mathbf{0}^r$$

$$\downarrow$$

$$\frac{dy^r}{dt} = - \left(\frac{\partial R^r}{\partial y^r} \right)^{-1} \left(\frac{\partial R^r}{\partial y^s} \right) \frac{dy^s}{dt}$$

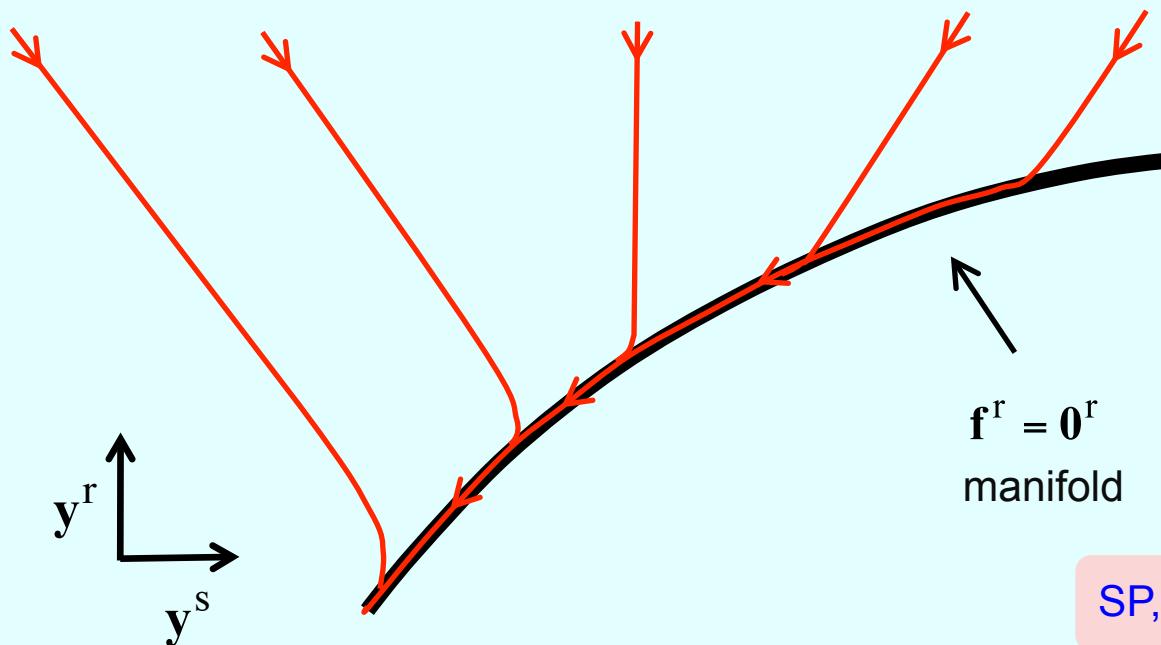
$$R^{r,f} - R^{r,b} = \mathbf{0}^r$$

$$\Rightarrow$$

$$\frac{d}{dt} \begin{bmatrix} y^r \\ y^s \end{bmatrix} = \begin{bmatrix} X_s^r \\ X_s^s \end{bmatrix} R^s$$



The fast/slow basis vectors of QSSA/PEA



$$\frac{dy}{dt} = S_r R^r + S_s R^s$$

$$\mathbf{f}^r = \mathbf{0}^r$$

manifold

SP, PEA, QSSA: different $\mathbf{a}_r \mathbf{a}_s$

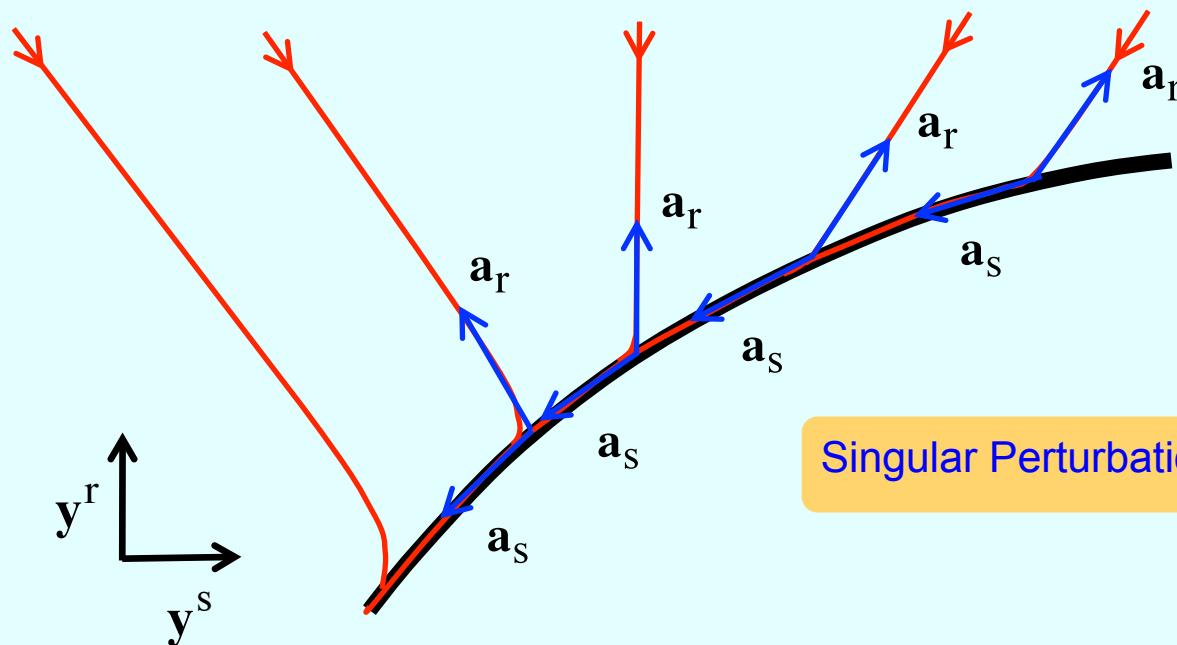
Singular Perturbations
PEA
QSSA

$$\Rightarrow \quad \frac{dy}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s \quad \Rightarrow$$

$$\mathbf{f}^r = \mathbf{0}^r$$
$$\frac{dy}{dt} = \mathbf{a}_s \mathbf{f}^s$$



The fast/slow basis vectors of CSP



$$\frac{dy}{dt} = \mathbf{S}_r \mathbf{R}^r + \mathbf{S}_s \mathbf{R}^s$$

Singular Perturbations: can adjust both \mathbf{a}_r \mathbf{a}_s

Singular Perturbations

PEA

QSSA

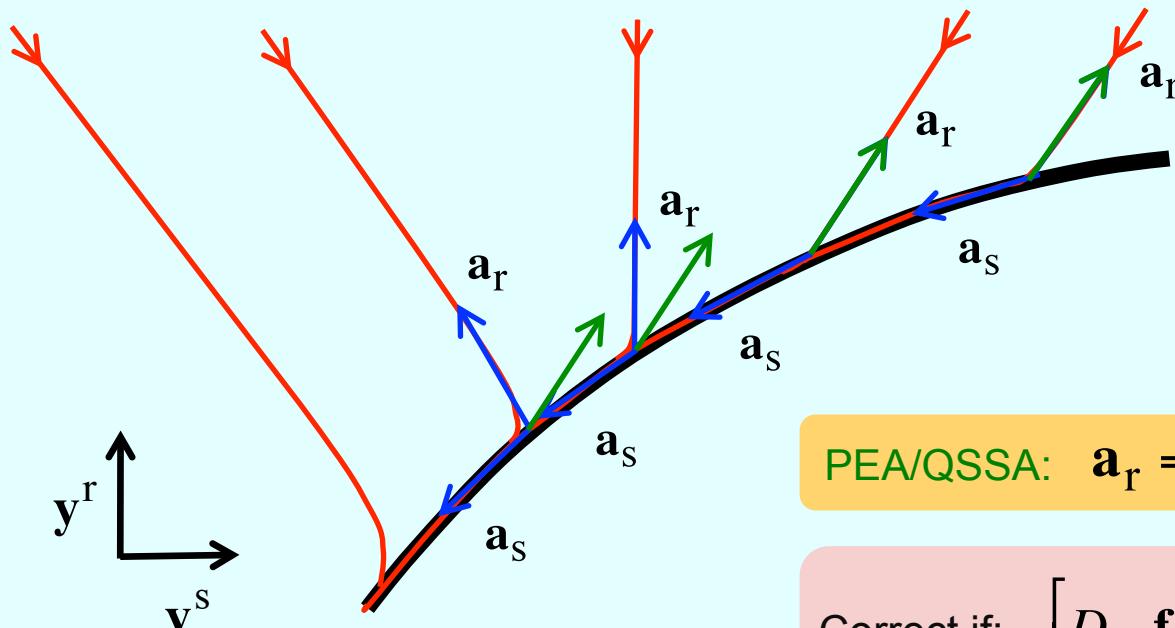
$$\Rightarrow \frac{dy}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s \Rightarrow$$

$$\mathbf{f}^r = \mathbf{0}^r$$

$$\frac{dy}{dt} = \mathbf{a}_s \mathbf{f}^s$$



The fast vectors of QSSA/PEA



$$\frac{dy}{dt} = S_r R^r + S_s R^s$$

$$\frac{d}{dt} \begin{bmatrix} y^r \\ y^s \end{bmatrix} = \begin{bmatrix} g^r \\ g^s \end{bmatrix}$$

PEA/QSSA: $\mathbf{a}_r = \mathbf{S}_r$

Correct if: $[D_{y^r} f^s] [D_{y^r} g^r]^{-1} = O(\varepsilon)$

Singular Perturbations

PEA

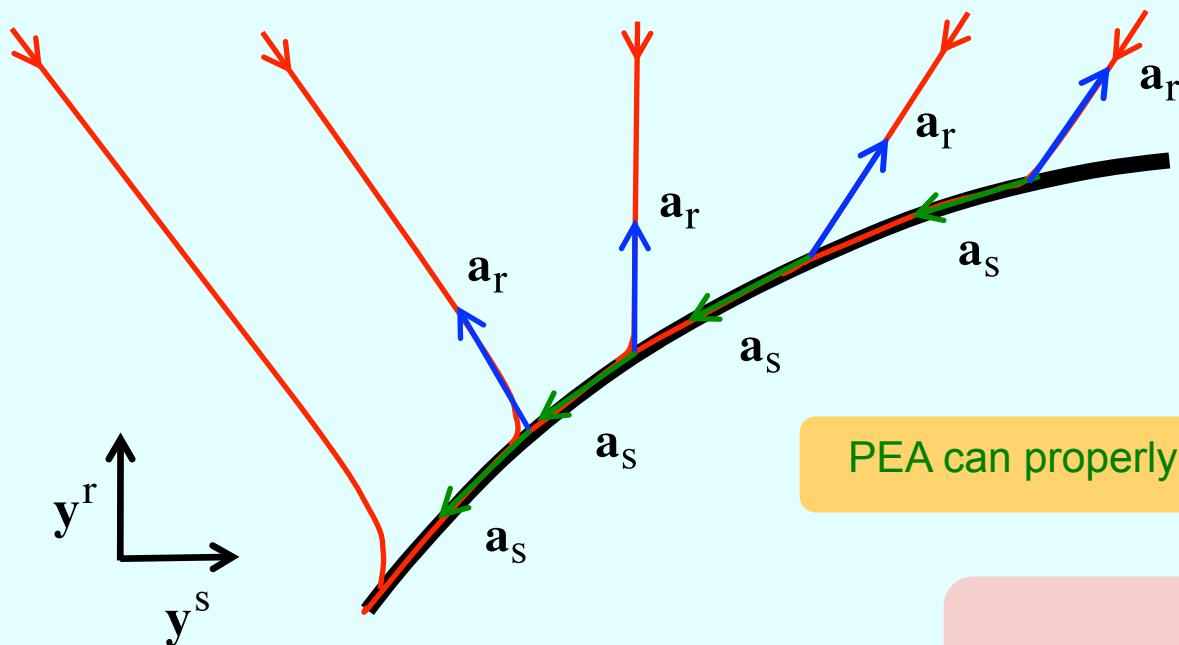
QSSA

$$\Rightarrow \frac{dy}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s \quad \Rightarrow \quad \mathbf{f}^r = \mathbf{0}^r$$

$$\frac{dy}{dt} = \mathbf{a}_s \mathbf{f}^s$$



The slow vectors of PEA



PEA can properly adjust \mathbf{a}_s

$$\frac{dy}{dt} = \mathbf{S}_r \mathbf{R}^r + \mathbf{S}_s \mathbf{R}^s$$

$$\frac{d}{dt} \begin{bmatrix} \mathbf{y}^r \\ \mathbf{y}^s \end{bmatrix} = \begin{bmatrix} \mathbf{g}^r \\ \mathbf{g}^s \end{bmatrix}$$

Correct if: $[D_{\mathbf{y}^r} \mathbf{g}^r]^{-1} [D_{\mathbf{a}_s} \mathbf{g}^r] = O(\varepsilon)$

Singular Perturbations

PEA

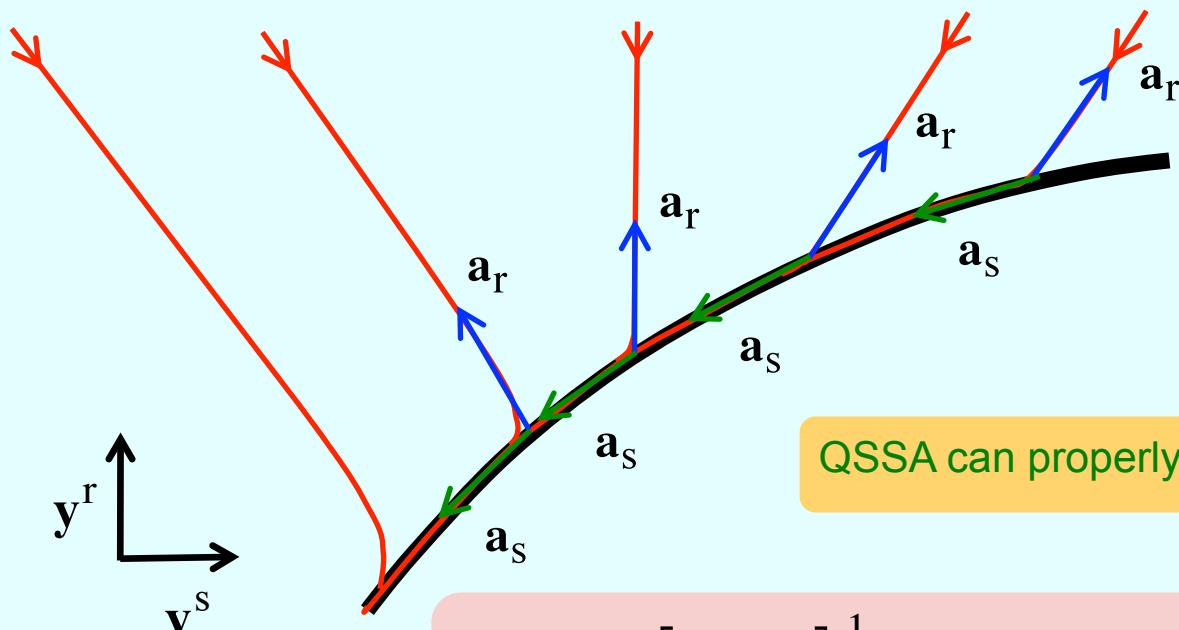
QSSA

$$\Rightarrow \frac{dy}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s \quad \Rightarrow \quad \mathbf{f}^r = \mathbf{0}^r$$

$$\frac{dy}{dt} = \mathbf{a}_s \mathbf{f}^s$$



The slow vectors of QSSA



correct if: $[D_{\mathbf{y}^r} \mathbf{g}^r]^{-1} [D_{\mathbf{a}_s} \mathbf{g}^r] = O(\varepsilon)$ $[D_{\mathbf{y}^r} \mathbf{R}^r]^{-1} [D_{\mathbf{y}^s} \mathbf{R}^r] = O(\varepsilon)$

Singular Perturbations

PEA

QSSA

$$\Rightarrow \frac{d\mathbf{y}}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s \Rightarrow$$

$$\mathbf{f}^r = \mathbf{0}^r$$

$$\frac{d\mathbf{y}}{dt} = \mathbf{a}_s \mathbf{f}^s$$

$$\frac{dy}{dt} = \mathbf{S}_r \mathbf{R}^r + \mathbf{S}_s \mathbf{R}^s$$

$$\frac{d}{dt} \begin{bmatrix} \mathbf{y}^r \\ \mathbf{y}^s \end{bmatrix} = \begin{bmatrix} \mathbf{g}^r \\ \mathbf{g}^s \end{bmatrix}$$



Criteria for the validity of the QSSA/PEA

$$\frac{d}{dt} \begin{bmatrix} \mathbf{y}^r \\ \mathbf{y}^s \end{bmatrix} = \mathbf{S}_r \mathbf{R}^r + \mathbf{S}_s \mathbf{R}^s = \begin{bmatrix} \mathbf{S}_r^r \\ \mathbf{S}_r^s \end{bmatrix} \mathbf{R}^r + \begin{bmatrix} \mathbf{S}_s^r \\ \mathbf{S}_s^s \end{bmatrix} \mathbf{R}^s = \begin{bmatrix} \mathbf{g}^r \\ \mathbf{g}^s \end{bmatrix} \quad \frac{d\mathbf{y}}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s$$

$$\left[D_{\mathbf{y}^r} \mathbf{f}^s \right] \left[D_{\mathbf{y}^r} \mathbf{g}^r \right]^{-1} = O(\varepsilon) \quad \xleftarrow{\hspace{1cm}} \quad \text{Stability of PEA and QSSA}$$

$$\left[D_{\mathbf{y}^r} \mathbf{g}^r \right]^{-1} \left[D_{\mathbf{a}_s} \mathbf{g}^r \right] = O(\varepsilon) \quad \xleftarrow{\hspace{1cm}} \quad \text{Accuracy of PEA}$$

$$\left[D_{\mathbf{y}^r} \mathbf{R}^r \right]^{-1} \left[D_{\mathbf{y}^s} \mathbf{R}^r \right] = O(\varepsilon) \quad \xleftarrow{\hspace{1cm}} \quad \text{Accuracy of QSSA}$$

[\mathbf{v}, \mathbf{c}'] [\mathbf{v}, \mathbf{c}] $^{-1}$

Goussis CTM 2012, C&F 2015



Meaning of the criteria for the validity of the QSSA/PEA

$$\frac{d}{dt} \begin{bmatrix} \mathbf{y}^r \\ \mathbf{y}^s \end{bmatrix} = \mathbf{S}_r \mathbf{R}^r + \mathbf{S}_s \mathbf{R}^s = \begin{bmatrix} \mathbf{S}_r^r \\ \mathbf{S}_s^s \end{bmatrix} \mathbf{R}^r + \begin{bmatrix} \mathbf{S}_s^r \\ \mathbf{S}_s^s \end{bmatrix} \mathbf{R}^s = \begin{bmatrix} \mathbf{g}^r \\ \mathbf{g}^s \end{bmatrix} \quad \frac{d\mathbf{y}}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s$$

$$\left[D_{\mathbf{y}^r} \mathbf{f}^s \right] \left[D_{\mathbf{y}^r} \mathbf{g}^r \right]^{-1} = O(\varepsilon) \quad \xleftarrow{\hspace{1cm}} \text{Stability of PEA and QSSA}$$

$$\mathbf{f}^s = \left(\mathbf{S}_s^s - \mathbf{S}_r^s \left(\mathbf{S}_r^r \right)^{-1} \mathbf{S}_s^r \right) \mathbf{R}^s \quad \mathbf{g}^r = \mathbf{S}_r^r \mathbf{R}^r + \mathbf{S}_s^r \mathbf{R}^s$$

The sensitivity of \mathbf{R}^r along \mathbf{y}^r is $O(\varepsilon^{-1})$ larger than that of \mathbf{R}^s

Only the M reactions in $\mathbf{S}_r \mathbf{R}^r$ contribute to the fast dynamics of \mathbf{y}^r



Meaning of the criteria for the validity of the QSSA/PEA

$$\frac{d}{dt} \begin{bmatrix} \mathbf{y}^r \\ \mathbf{y}^s \end{bmatrix} = \mathbf{S}_r \mathbf{R}^r + \mathbf{S}_s \mathbf{R}^s = \begin{bmatrix} \mathbf{S}_r^r \\ \mathbf{S}_r^s \end{bmatrix} \mathbf{R}^r + \begin{bmatrix} \mathbf{S}_s^r \\ \mathbf{S}_s^s \end{bmatrix} \mathbf{R}^s = \begin{bmatrix} \mathbf{g}^r \\ \mathbf{g}^s \end{bmatrix} \quad \frac{d\mathbf{y}}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s$$

$$\left[D_{\mathbf{y}^r} \mathbf{g}^r \right]^{-1} \left[D_{\mathbf{a}_s} \mathbf{g}^r \right] = O(\varepsilon) \quad \xleftarrow{\hspace{1cm}} \text{Accuracy of PEA}$$

The sensitivity of \mathbf{g}^r along \mathbf{y}^r is $O(\varepsilon^{-1})$ larger than that of \mathbf{g}^r along \mathbf{a}_s

\mathbf{R}^r is $O(\varepsilon^{-1})$ more sensitive to perturbations of \mathbf{y}^r than \mathbf{R}^s is sensitive to perturbations of \mathbf{y}^r and \mathbf{y}^s along the manifold



Meaning of the criteria for the validity of the QSSA/PEA

$$\frac{d}{dt} \begin{bmatrix} \mathbf{y}^r \\ \mathbf{y}^s \end{bmatrix} = \mathbf{S}_r \mathbf{R}^r + \mathbf{S}_s \mathbf{R}^s = \begin{bmatrix} \mathbf{S}_r^r \\ \mathbf{S}_r^s \end{bmatrix} \mathbf{R}^r + \begin{bmatrix} \mathbf{S}_s^r \\ \mathbf{S}_s^s \end{bmatrix} \mathbf{R}^s = \begin{bmatrix} \mathbf{g}^r \\ \mathbf{g}^s \end{bmatrix} \quad \frac{d\mathbf{y}}{dt} = \mathbf{a}_r \mathbf{f}^r + \mathbf{a}_s \mathbf{f}^s$$

$$[D_{\mathbf{y}^r} \mathbf{g}^r]^{-1} [D_{\mathbf{a}_s} \mathbf{g}^r] = O(\varepsilon)$$

$$[D_{\mathbf{y}^r} \mathbf{R}^r]^{-1} [D_{\mathbf{y}^s} \mathbf{R}^r] = O(\varepsilon)$$

Accuracy of QSSA

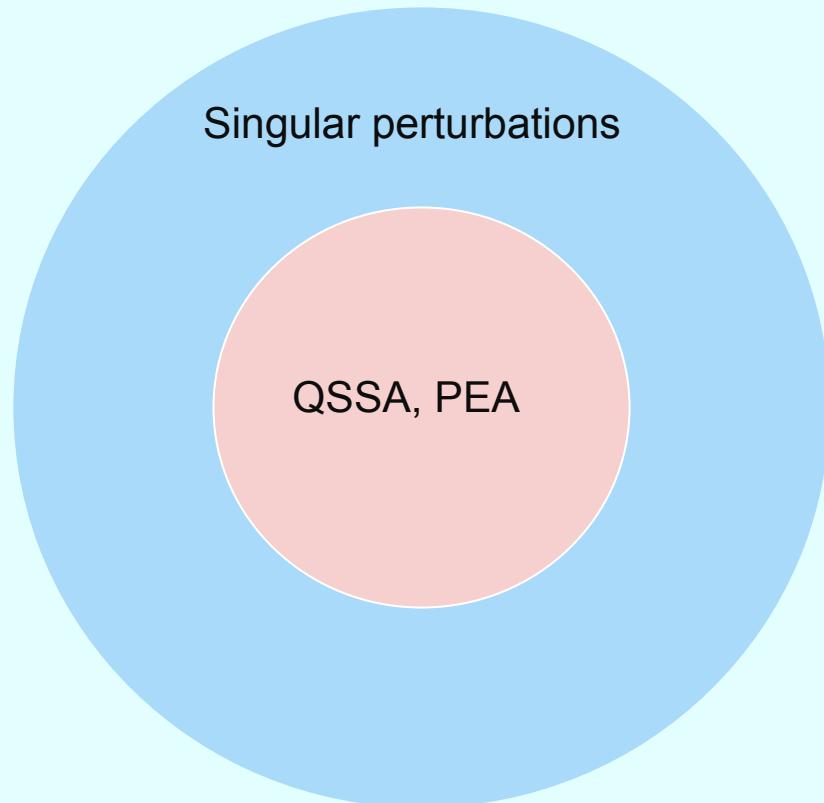
\mathbf{R}^r is $O(\varepsilon^{-1})$ more sensitive to perturbations of \mathbf{y}^r than \mathbf{R}^s is sensitive to perturbations of \mathbf{y}^r and \mathbf{y}^s

\mathbf{R}^r is $O(\varepsilon^{-1})$ more sensitive to perturbations of \mathbf{y}^r than \mathbf{R}^r is sensitive to perturbations of \mathbf{y}^s

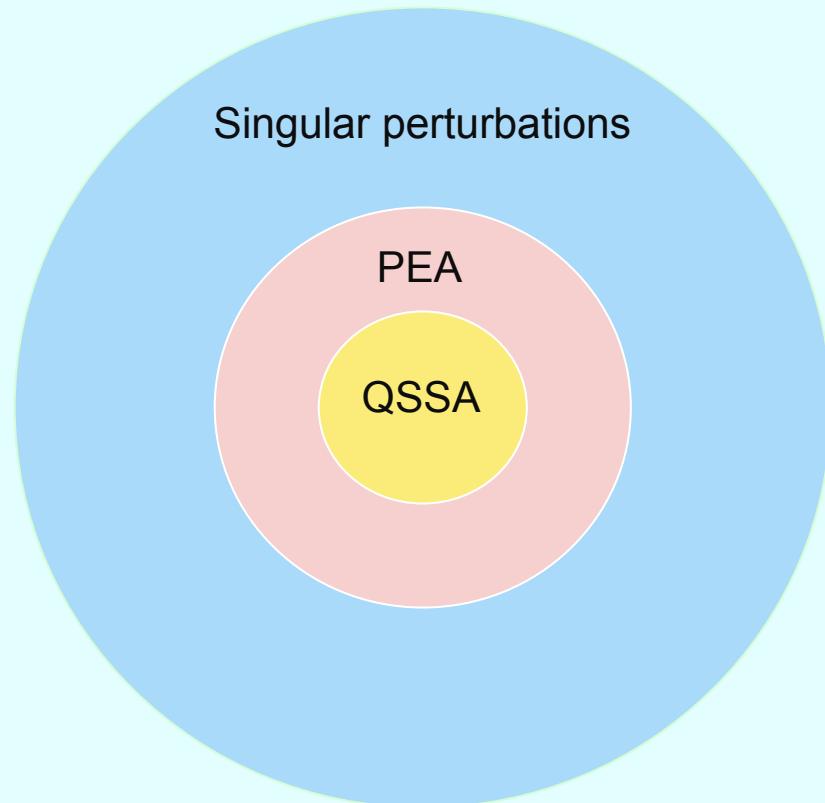


QSSA/PEA: stability and accuracy

Stability

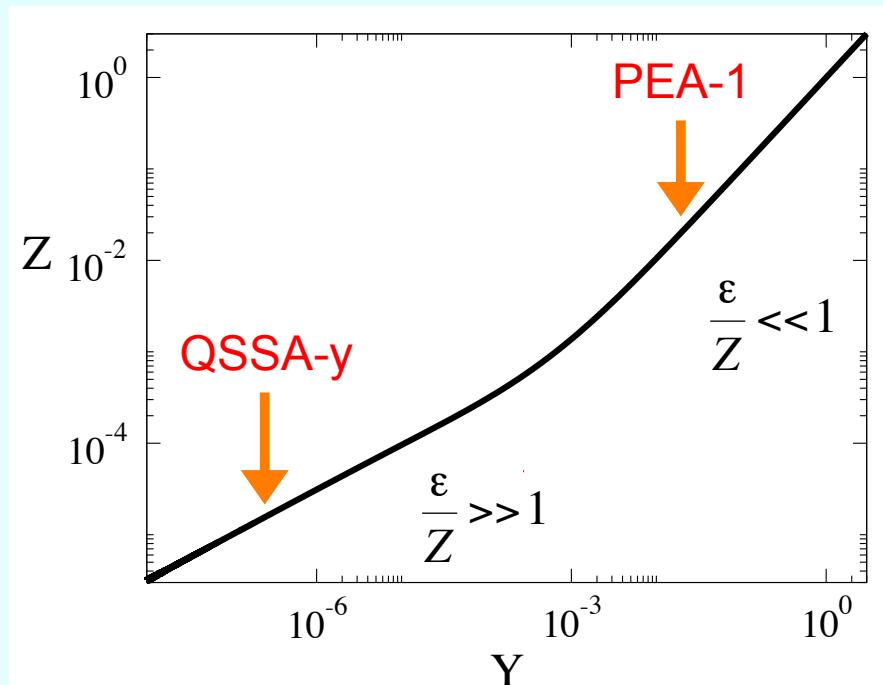
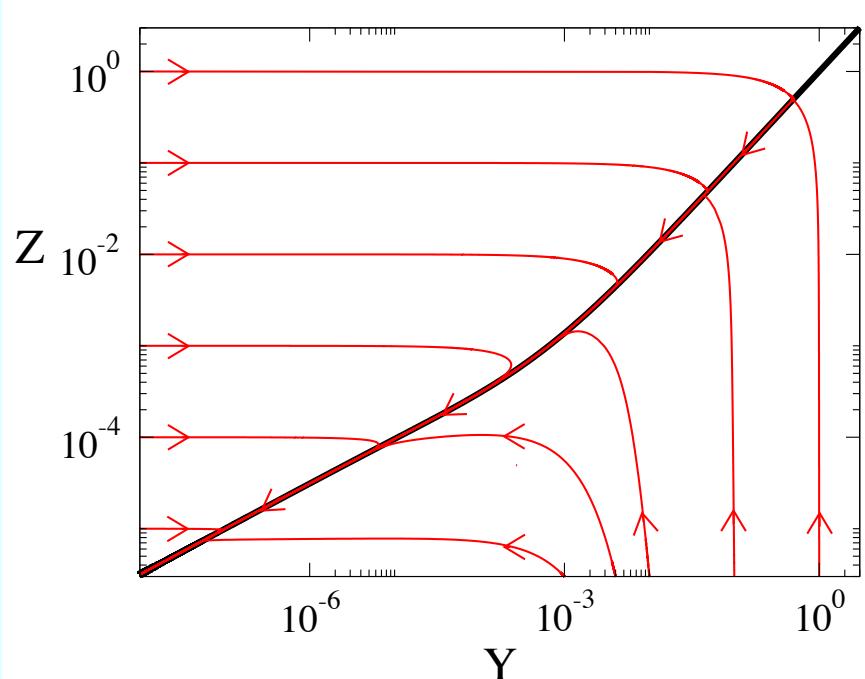


Accuracy



Simple example

$$\frac{d}{dt} \begin{bmatrix} Y \\ Z \end{bmatrix} = \begin{bmatrix} +1 \\ -1 \end{bmatrix} \frac{1}{\varepsilon} Z^2 + \begin{bmatrix} -1 \\ +1 \end{bmatrix} \frac{1}{\varepsilon} YZ + \begin{bmatrix} -1 \\ 0 \end{bmatrix} Y$$



Simple example

$$\frac{d}{dt} \begin{bmatrix} Y \\ Z \end{bmatrix} = \begin{bmatrix} +1 \\ -1 \end{bmatrix} \frac{1}{\varepsilon} Z^2 + \begin{bmatrix} -1 \\ +1 \end{bmatrix} \frac{1}{\varepsilon} YZ + \begin{bmatrix} -1 \\ 0 \end{bmatrix} Y$$

$$\frac{\varepsilon}{Z} \ll 1$$

1st fast reaction
Y fast variable

$$\left[D_{y^r} f^s \right] \left[D_{y^r} g^r \right]^{-1} = \frac{\varepsilon}{Z + \varepsilon}$$

Stability of PEA and QSSA

OK

$$\left[D_{y^r} g^r \right]^{-1} \left[D_{a_s} g^r \right] = \frac{\varepsilon}{Z + \varepsilon}$$

Accuracy of PEA

OK

$$\left[D_{y^r} R^r \right]^{-1} \left[D_{y^s} R^r \right] = 1$$

Accuracy of QSSA

not OK



Simple example

$$\frac{d}{dt} \begin{bmatrix} Y \\ Z \end{bmatrix} = \begin{bmatrix} +1 \\ -1 \end{bmatrix} \frac{1}{\varepsilon} Z^2 + \begin{bmatrix} -1 \\ +1 \end{bmatrix} \frac{1}{\varepsilon} YZ + \begin{bmatrix} -1 \\ 0 \end{bmatrix} Y$$

$$\frac{\varepsilon}{Z} \gg 1$$

2nd fast reaction
Y fast variable

$$\left[D_{y^r} f^s \right] \left[D_{y^r} g^r \right]^{-1} = \frac{Z}{\varepsilon + Z} \quad \text{Stability of PEA and QSSA} \quad \text{OK}$$

$$\left[D_{y^r} g^r \right]^{-1} \left[D_{a_s} g^r \right] = \frac{Z}{\varepsilon + Z} \quad \text{Accuracy of PEA} \quad \text{OK}$$

$$\left[D_{y^r} R^r \right]^{-1} \left[D_{y^s} R^r \right] = 0 \quad \text{Accuracy of QSSA} \quad \text{OK}$$



Fast species and reactions

Fast species

The M species whose axis is most aligned with the M fast directions

Fast reactions

The M reaction rates that exhibit the largest slope in the fast subspace

Goussis CTM 2012, C&F 2015



H₂-air ignition

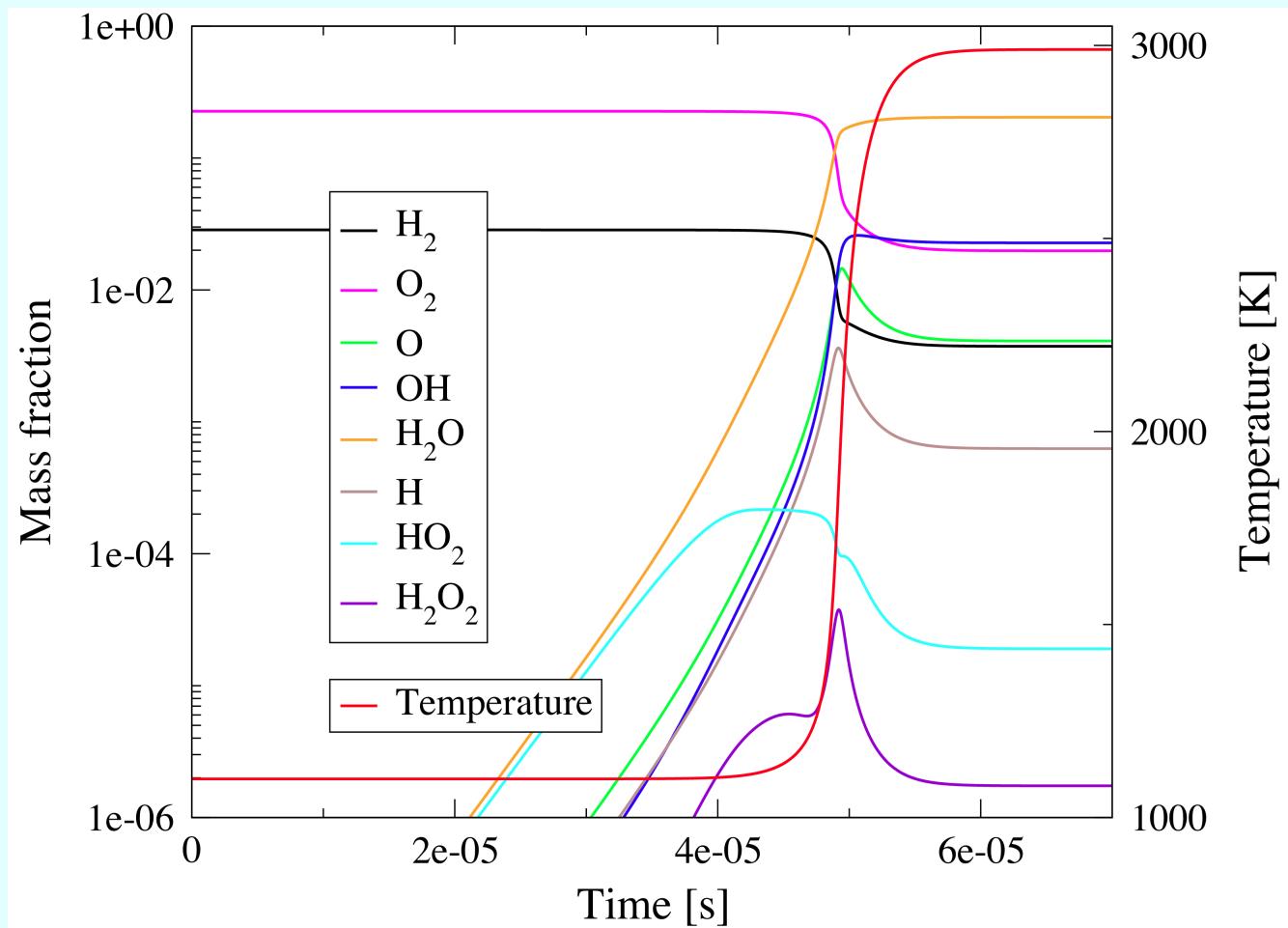
1. H+O₂ <=> OH+O
2. H₂+O <=> OH+H
3. H₂+OH <=> H₂O+H
4. H₂O+O <=> 2 OH
5. 2 H+M <=> H₂+M
6. H+OH+M <=> H₂O+M
7. 2 O+M <=> O₂+M
8. H+O+M <=> OH+M
9. O+OH+M <=> HO₂+M
10. H+O₂ (+M) <=> HO₂
11. HO₂+H <=> 2 OH
12. HO₂+H <=> H₂+O₂
13. HO₂+H <=> H₂O+O
14. HO₂+O <=> OH+O₂
15. HO₂+OH <=> H₂O+O₂
16. 2 OH(+M) <=> H₂O₂ (+M)
17. 2 HO₂ <=> H₂O₂+O₂
18. H₂O₂+H <=> HO₂+H₂
19. H₂O₂+H <=> H₂O+OH
20. H₂O₂+OH <=> H₂O+HO₂
21. H₂O₂+O <=> HO₂+OH

Adiabatic ignition of stoichiometric mixture at constant volume; T₀=1100K, p₀=2bar

Boivin et. al, Proc. Combust. Inst., 33:517-523, 2011



H₂-air ignition: profiles



Adiabatic ignition of stoichiometric mixture at constant volume; $T_0=1100\text{K}$, $p_0=2\text{bar}$



H₂-air ignition: 3-steps QSSA reduced mechanism

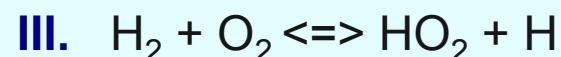
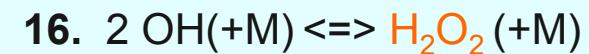
Species: 8

Conservation laws: 2 (O, H)

QSSA: 3 (O, OH, H₂O₂)

Steps: 8 - 3 - 2 = 3

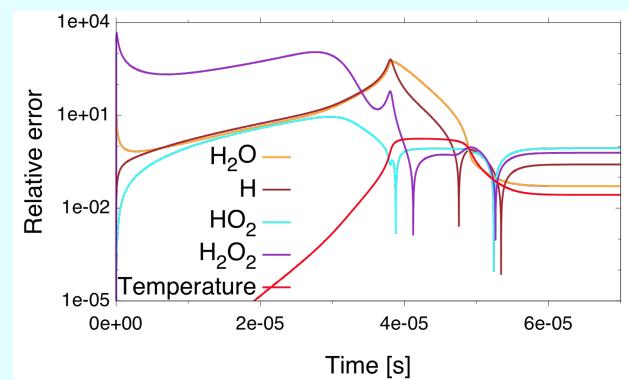
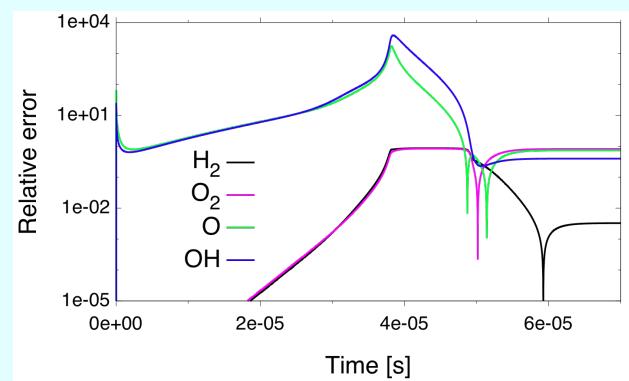
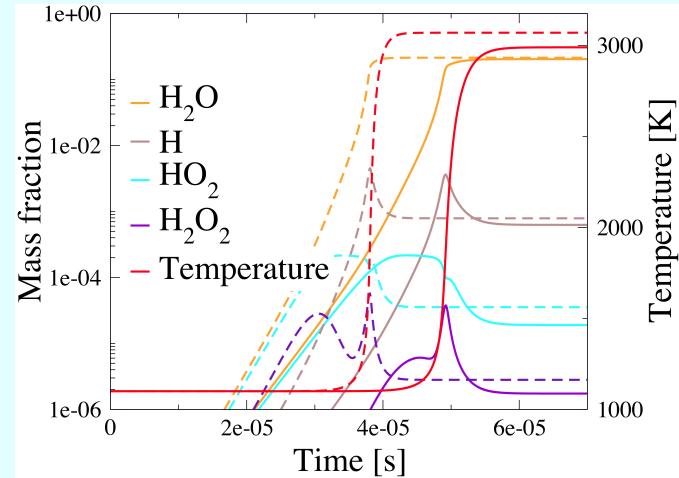
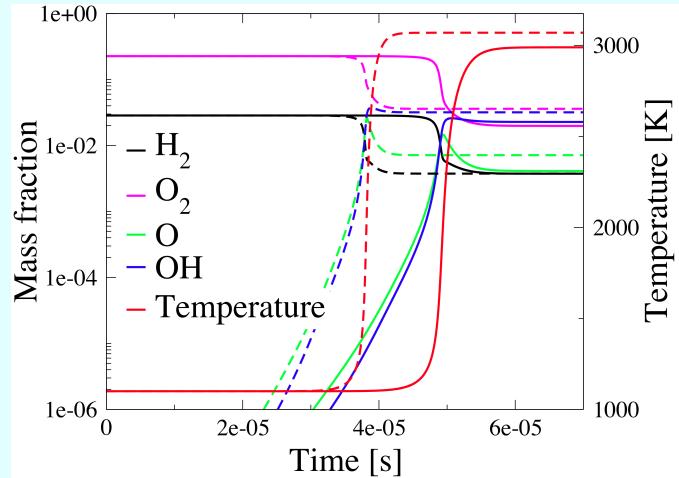
Fast reactions



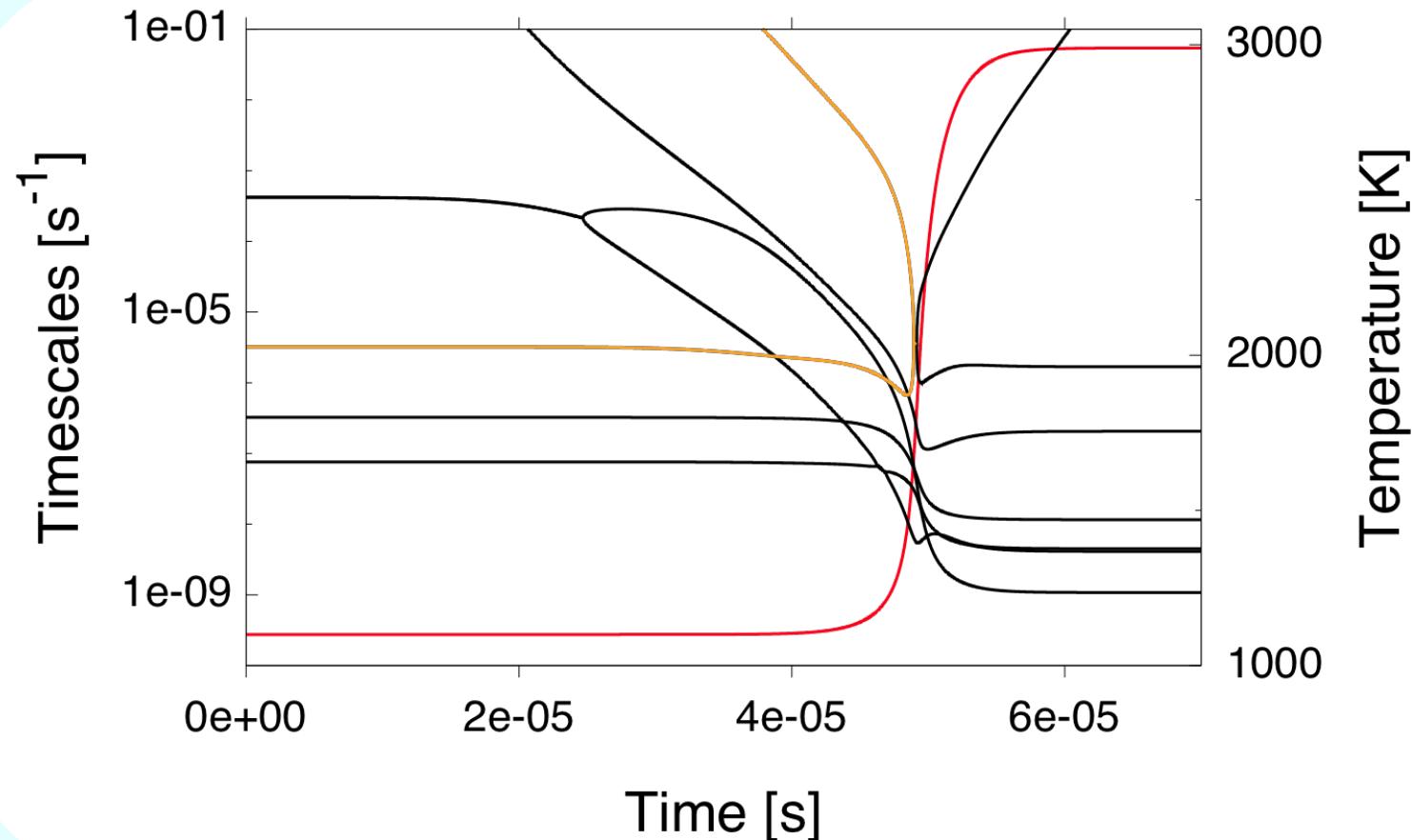
Boivin et. al, Proc. Combust. Inst., 33:517-523, 2011



H_2 -air ignition: 3-steps QSSA reduced mechanism



H₂-air ignition: timescales

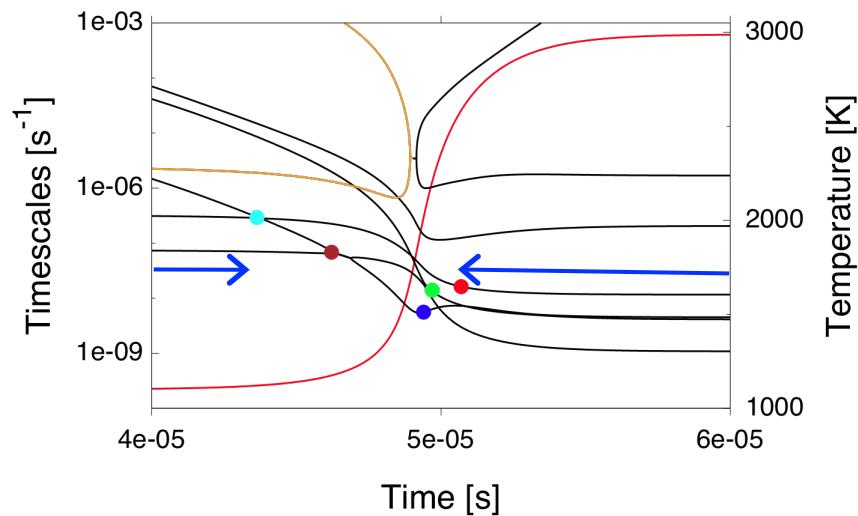
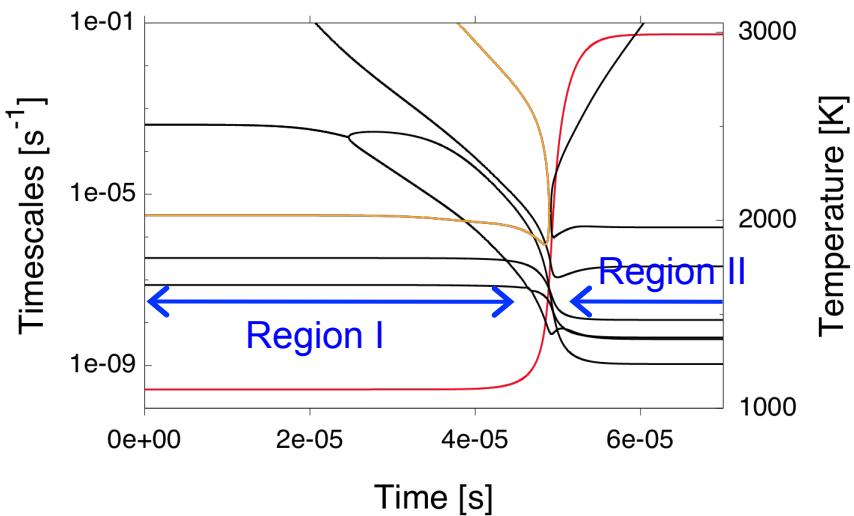


Explosive/Dissipative

Temperature



H_2 -air ignition: timescales

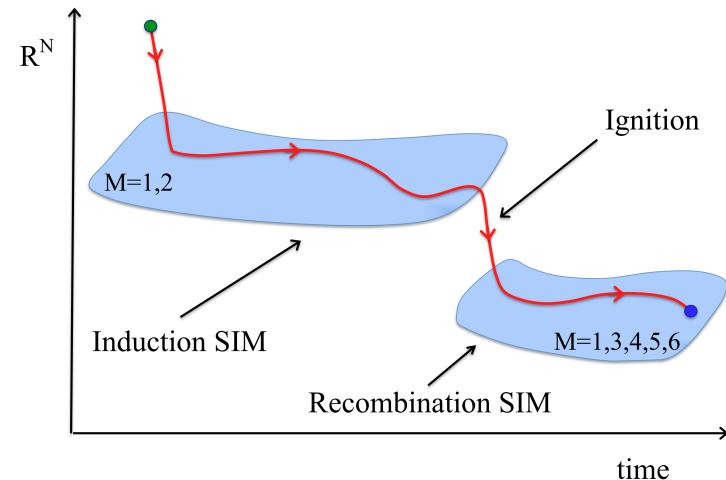
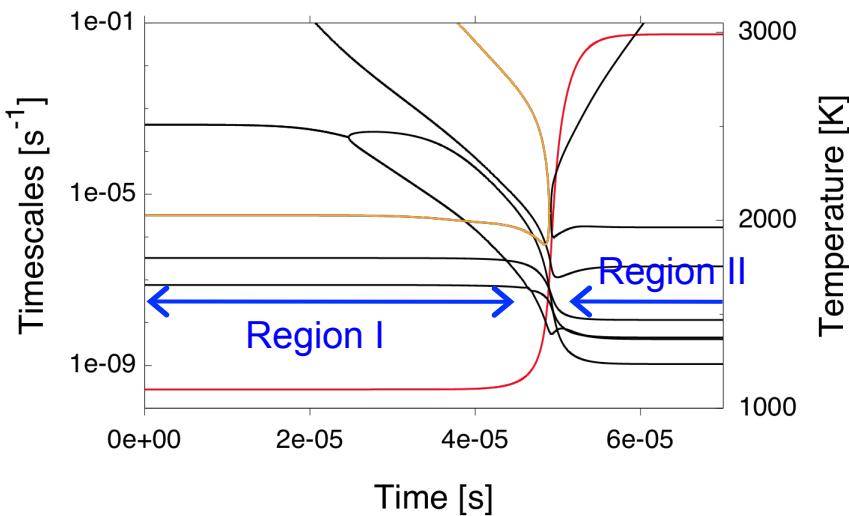


Explosive/Dissipative

Temperature



H₂-air ignition: manifolds



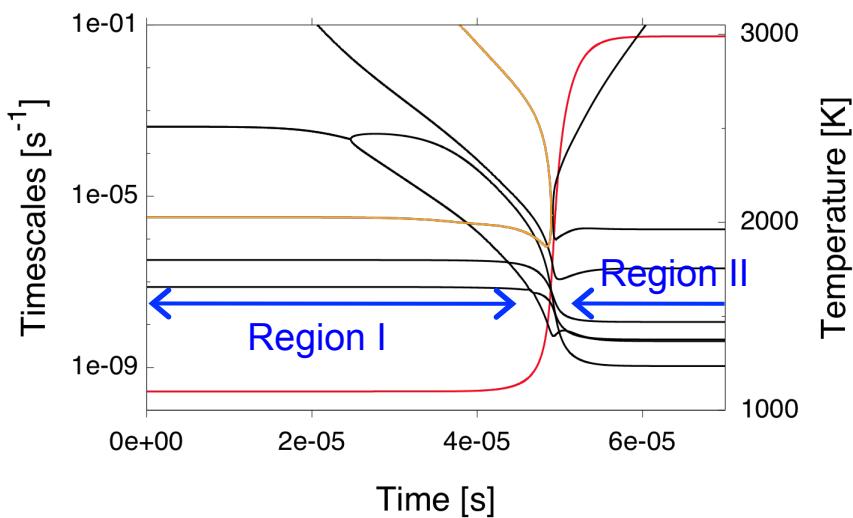
Induction SIM: up to **2** approximations (QSSA, PEA, etc)

Recombination SIM: up to **6** approximations (QSSA, PEA, etc)

Kourdis, PhD Thesis, NTUA 2012



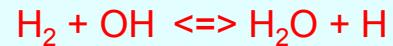
H₂-air ignition: manifolds



Region I (M=1, 2)

Fast species: O, OH

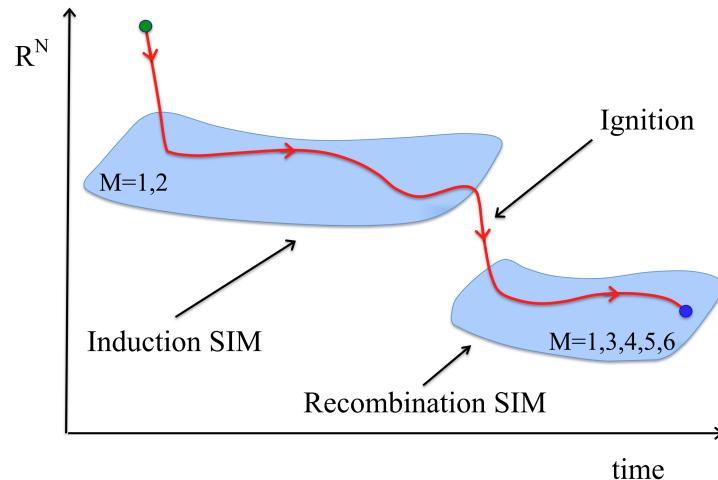
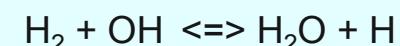
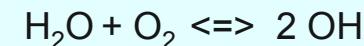
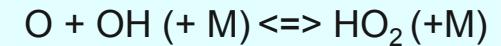
Fast reactions: $H_2 + O \leftrightarrow OH + H$



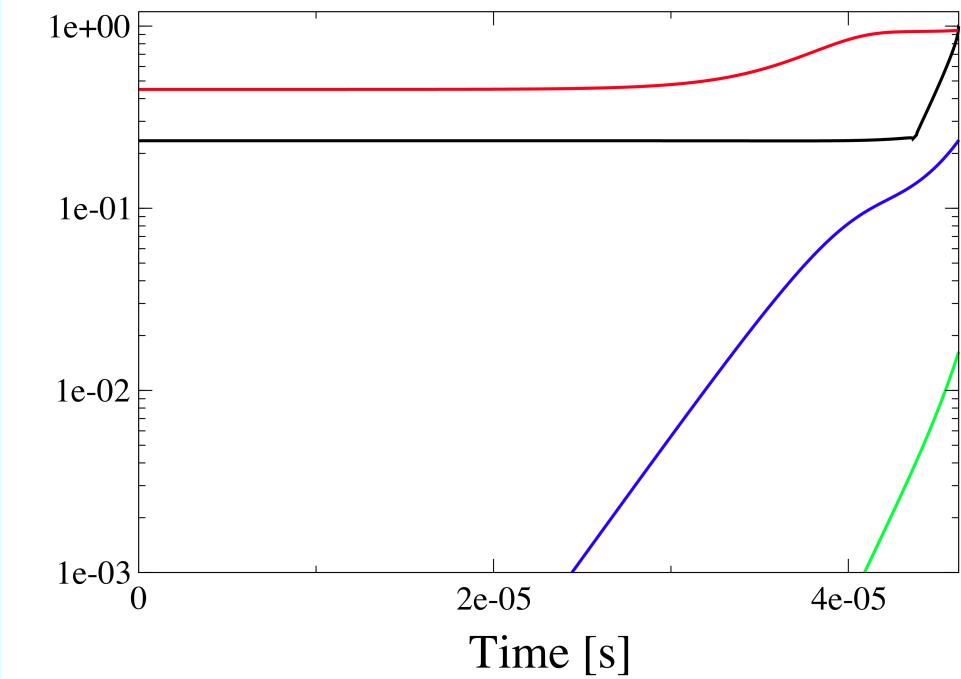
Region II (M=4)

Fast species: H₂O₂, HO₂, O, H

Fast reactions: $2OH (+M) \leftrightarrow H_2O_2 (+M)$



Region I (M=1): QSSA/PEA



$$\varepsilon = \frac{\tau_1, \text{ slowest of fast}}{\tau_2, \text{ fastest of slow}}$$

$$\left[D_{\mathbf{y}^r} \mathbf{f}^s \right] \left[D_{\mathbf{y}^r} \mathbf{g}^r \right]^{-1} = O(\varepsilon) \quad \text{Stability QSSA/PEA}$$

$$\left[D_{\mathbf{y}^r} \mathbf{g}^r \right]^{-1} \left[D_{\mathbf{a}_s} \mathbf{g}^r \right] = O(\varepsilon) \quad \text{Accuracy PEA}$$

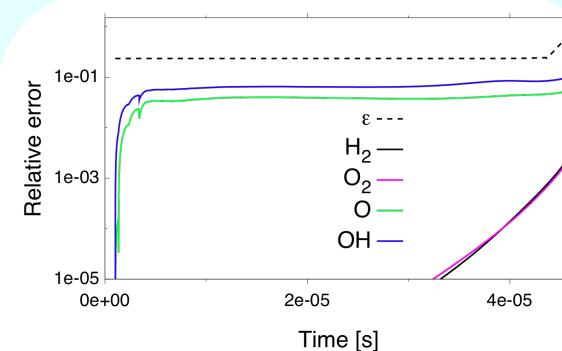
$$\left[D_{\mathbf{y}^r} \mathbf{R}^r \right]^{-1} \left[D_{\mathbf{y}^s} \mathbf{R}^r \right] = O(\varepsilon) \quad \text{PEA -> QSSA}$$

QSSA/PEA stability OK
 PEA accuracy OK (?)
 PEA->QSSA OK

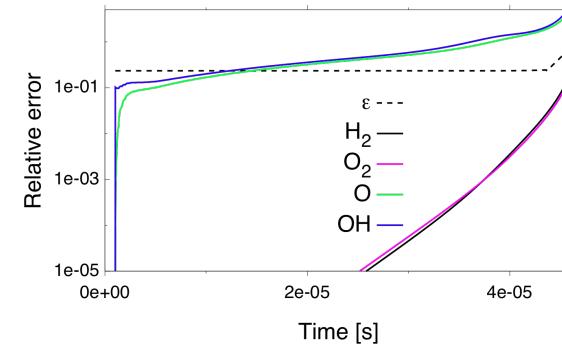


Region I ($M=1$), QSSA/PEA: accuracy

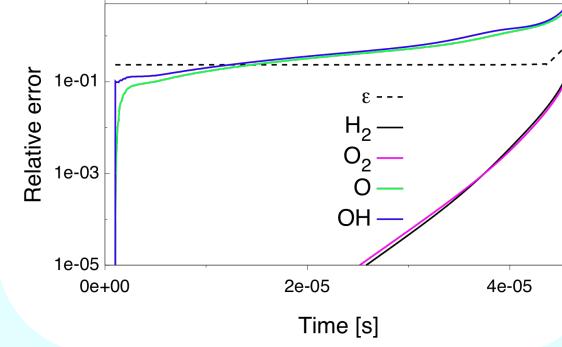
CSP



PEA



QSSA

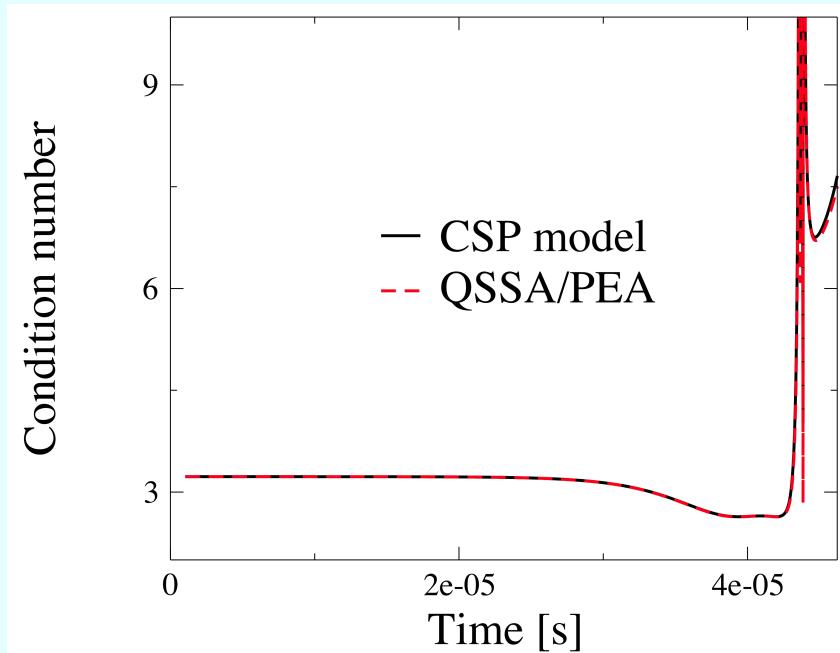


Asymptotics OK

PEA accuracy OK (?)
PEA->QSSA OK



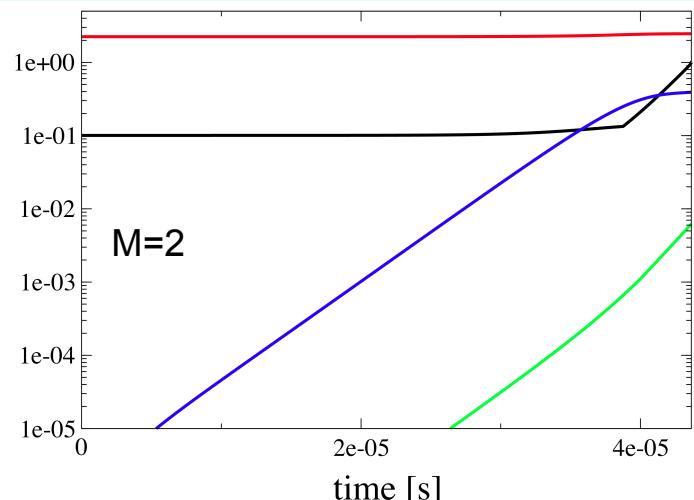
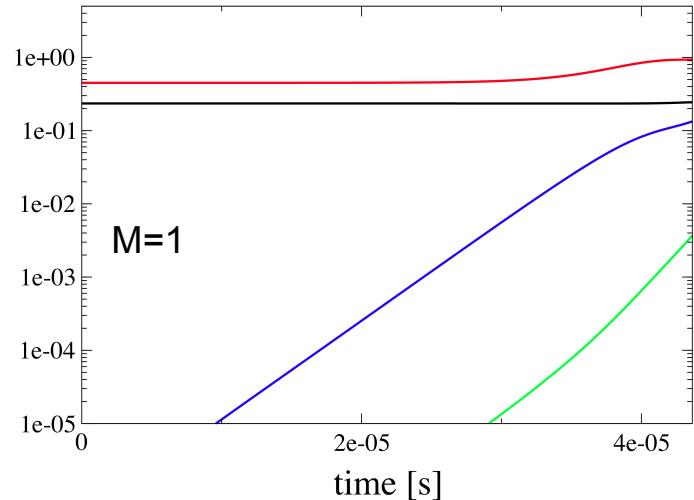
Region I ($M=1$), QSSA/PEA: stability



QSSA/PEA stability	ok
PEA accuracy	ok (?)
PEA->QSSA	ok



Region I (M=1 and 2): QSSA/PEA



$$\varepsilon = \frac{\tau_1 \text{ or } 2, \text{ slowest of fast}}{\tau_2 \text{ or } 3, \text{ fastest of slow}}$$

$$\left[D_{y^r} f^s \right] \left[D_{y^r} g^r \right]^{-1} = O(\varepsilon) \quad \text{Stability QSSA/PEA}$$

$$\left[D_{y^r} g^r \right]^{-1} \left[D_{a_s} g^r \right] = O(\varepsilon) \quad \text{Accuracy PEA}$$

$$\left[D_{y^r} R^r \right]^{-1} \left[D_{y^s} R^r \right] = O(\varepsilon) \quad \text{PEA -> QSSA}$$

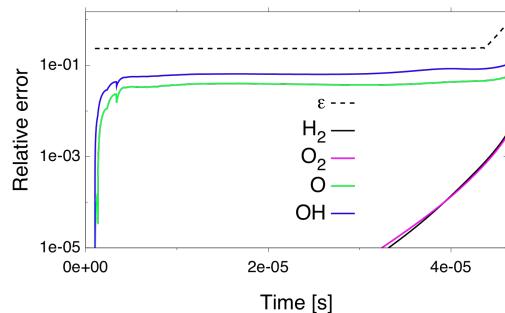
QSSA/PEA stability	M=1: ok	M=2: ok
PEA accuracy	M=1: ok	M=2: not so
PEA->QSSA	M=1: ok	M=2: ok



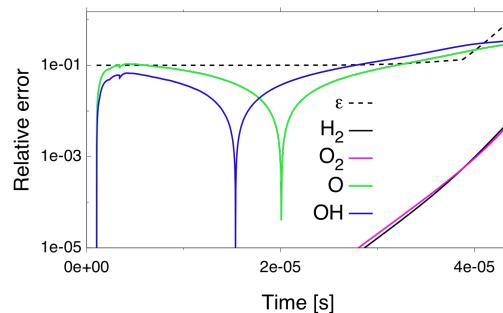
Region I ($M=1$ and 2), QSSA/PEA: accuracy

CSP

$M=1$



$M=2$

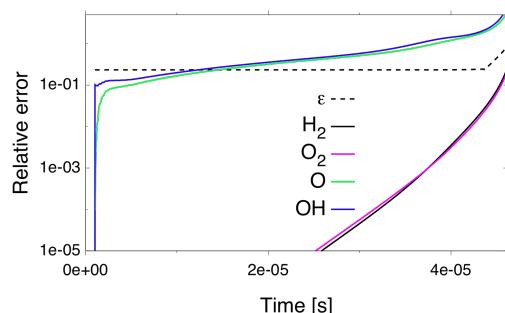


PEA

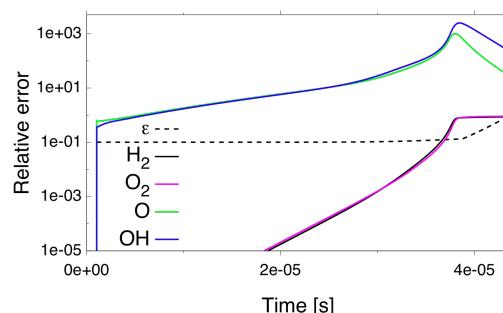
Asymptotics ok

$M=1$

PEA accuracy ok (?)
 PEA->QSSA ok



Time [s]

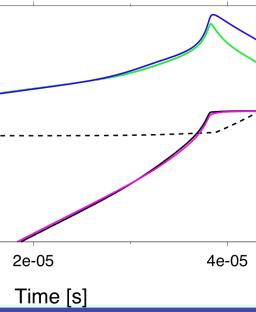
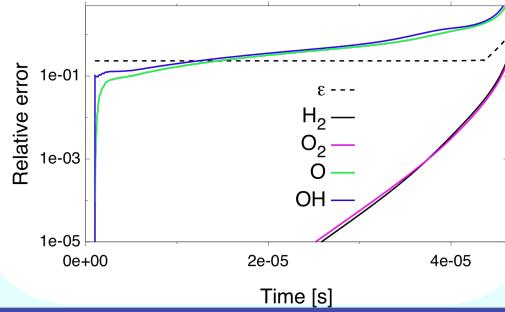


Time [s]

QSSA

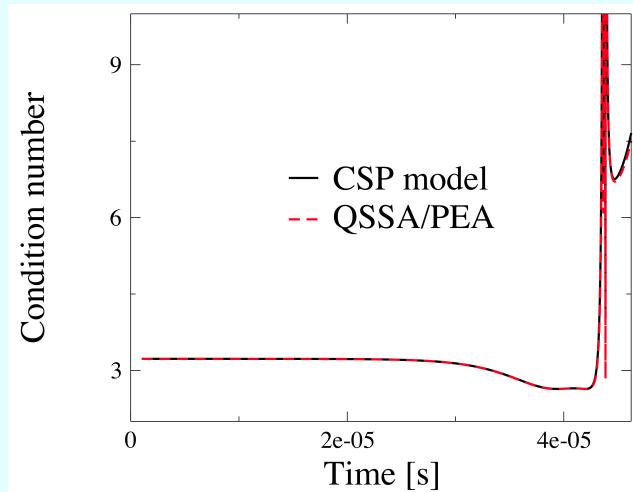
$M=2$

PEA accuracy not ok
 PEA->QSSA ok



Region I (M=2), QSSA/PEA: stability

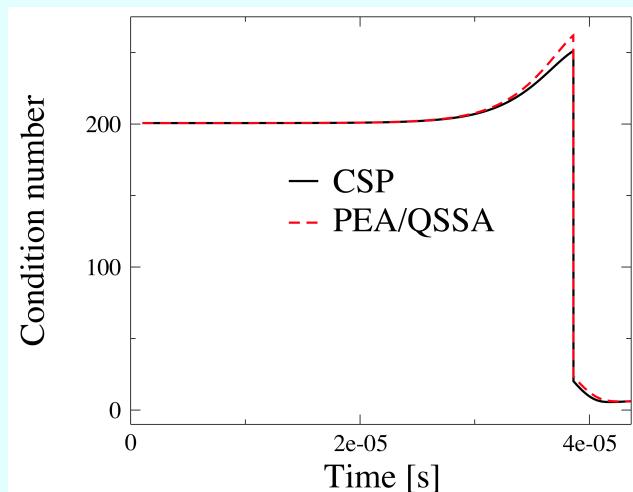
M=1



M=1

QSSA/PEA stability	ok
PEA accuracy	ok (?)
PEA->QSSA	ok

M=2

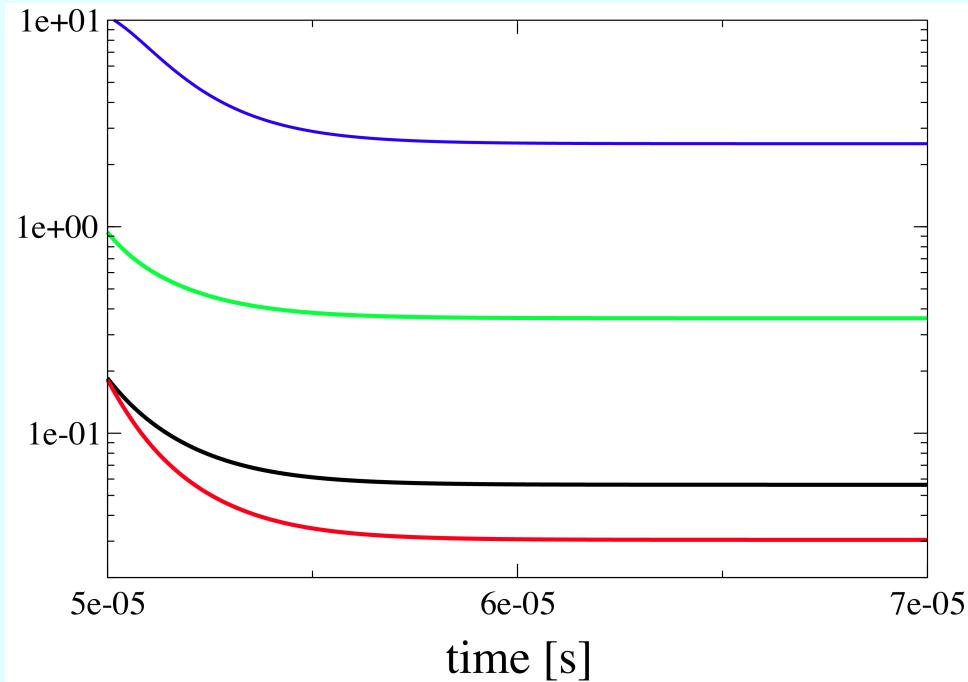


M=2

QSSA/PEA stability	ok
PEA accuracy	not ok
PEA->QSSA	ok



Region II (M=4): QSSA/PEA



$$\varepsilon = \frac{\tau_4, \text{ slowest of fast}}{\tau_5, \text{ fastest of slow}}$$

$$\left[D_{\mathbf{y}^r} \mathbf{f}^s \right] \left[D_{\mathbf{y}^r} \mathbf{g}^r \right]^{-1} = O(\varepsilon) \quad \text{Stability QSSA/PEA}$$

$$\left[D_{\mathbf{y}^r} \mathbf{g}^r \right]^{-1} \left[D_{\mathbf{a}_S} \mathbf{g}^r \right] = O(\varepsilon) \quad \text{Accuracy PEA}$$

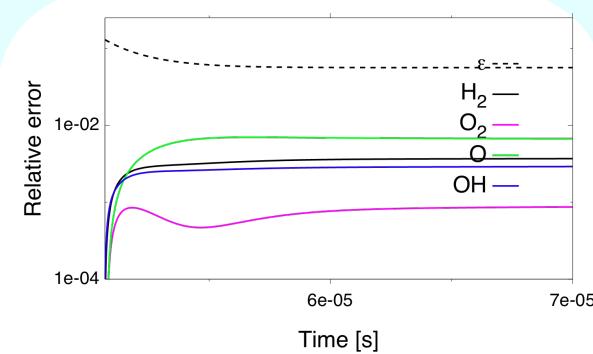
$$\left[D_{\mathbf{y}^r} \mathbf{R}^r \right]^{-1} \left[D_{\mathbf{y}^s} \mathbf{R}^r \right] = O(\varepsilon) \quad \text{PEA ->QSSA}$$

QSSA/PEA stability	not ok
PEA accuracy	ok
PEA->QSSA	not ok



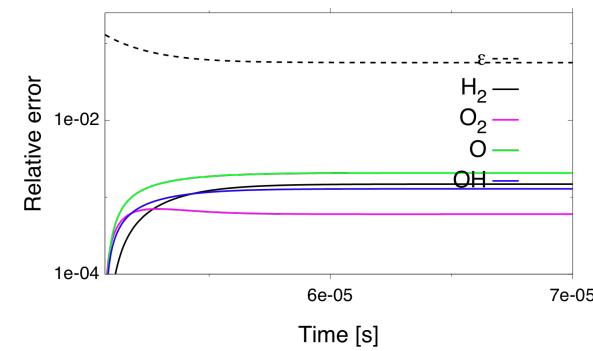
Region II (M=4), QSSA/PEA: accuracy

CSP



Asymptotics: OK

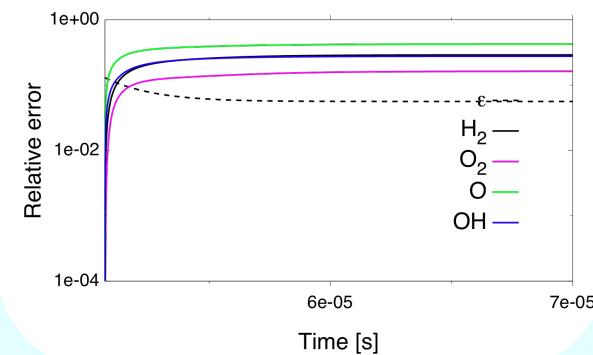
PEA



PEA accuracy
PEA->QSSA

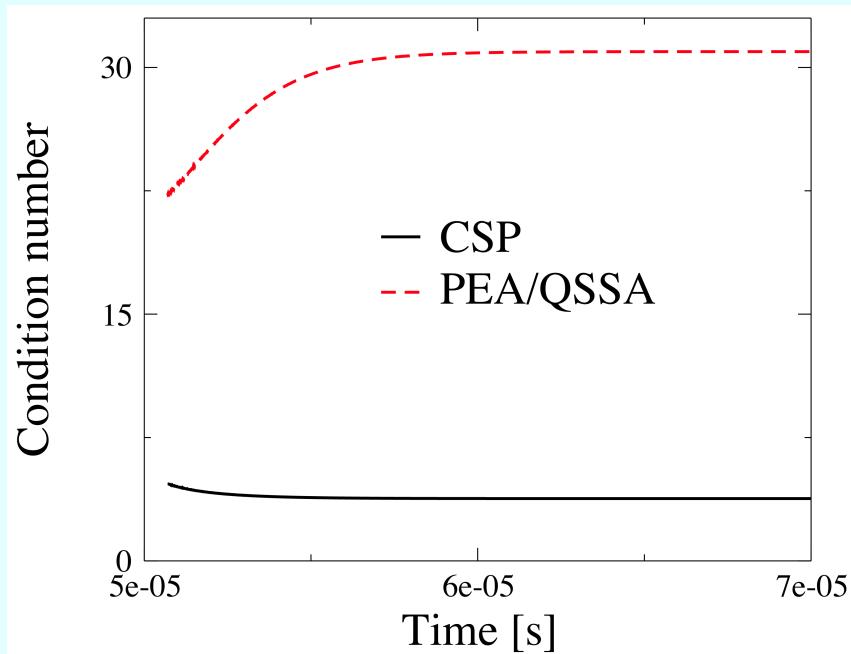
ok
not ok

QSSA



NTUA

Region II (M=4), QSSA/PEA: stability



QSSA/PEA stability not ok
PEA accuracy ok
PEA->QSSA not ok



Conclusions

There exist algorithms that can identify:

1. The number of fast time scales
2. The fast variables
3. The fast reactions
4. The possible validity of the QSSA/PEA

